# Dynamic Analysis of Earth Dam and Embankments under Earthquake Force

#### Indrajit Chowdhury<sup>1</sup> and Shambhu P. Dasgupta<sup>2</sup>

| Key words  | Abstract: This paper presents a generalized solution for dynamic analysis of earth dam based on   |
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| Clay core, dynamic response,<br>earth dam, factor of safety,<br>modes of vibration, variable | modal response technique. Formulation for dynamic response takes care of both homogenous dams and dams with internal clay core. A technique based on distribution of static stiffness has been evolved to evaluate factor of safety (FOS) for a dam with internal clay core.  |
| shear modulus.   | It also furnishes formulation for dynamic analysis when the dynamic shear modulus varies with depth of the dam and proposes a modified method for stability analysis that tries to combine the pseudo static method of slip circle and sliding block technique to arrive at a rational factor of safety under earthquake loading. |
|  | The method being analytic in nature does not require a sophisticated software development, a simple spread sheet or a MATHCAD shell would suffice for the same. Wherever possible, results have been compared with existing solutions.  |

# Introduction

Earth dams and embankments play an important role in irrigation, flood control and development of rail road infrastructure. Considering their functional requirement and importance in serving the community, it becomes imperative that they remain operational even after a strong motion earthquake with minimum damage.

The major analytical techniques that are popular for earthquake analysis of such dams are those developed by Mononobe (1936), Makdisi & Seed (1977), Gazetas (1982) and finally numerical analysis, based on Finite Element Method (FEM) as proposed by Clough & Chopra (1966) to name only the pioneering few.

Of all these techniques the first three methods are analytical in nature, where the dam is considered as a triangular homogenous shear beam and a solution is sought, based on its equation of motion in one dimension under seismic force. Gazetas's analytical formulation is usually considered to be most rigorous (Kramer 1984), while Seed's method can cater to nonlinear deformation of dam based on hyperbolic stiffness degradation of soil which is a function of induced strain level due to vibration (Seed & Idriss, 1971).

Finite element method (FEM) obviously gives the most exhaustive solution, but is not without its limitation. For other than exhaustive data preparation and input requirement – that makes the analysis expensive; if proper constitutive model cannot be fitted

into the mathematical model, it can often yield unrealistic result. In many cases it is difficult to fit an earth dam problem into a general purpose finite element software thus necessitating development of special purpose software which is not always readily available commercially.

It is for this, analytical methods as mentioned above have remained more popular around the world because of their simplicity in application, though they suffer from deficiencies in many cases. For instance, all methods cited above assume the dam to be a perfect triangle (i.e. crest area is zero) while in reality it is not. As a matter fact United States Bureau of Reclamation of small dams suggests an empirical formula for crest width (B<sub>t</sub>) and height H as B<sub>t</sub>= H/5+10(in FPS unit).A dam always has some finite dimension at crest for maintenance and inspection. How much this data affects its dynamic response is not very apparent.

Both Mononobe (1936), Makdisi & Seed(1877) gave solution assuming the dynamic shear modulus (G) constant with depth, while this would hardly be the case in real field condition. It has been found that G varies with height (H) of the dam. Gazetas (1982) proposed a formulation where he considered G to vary with depth (z) as G (z/H)<sup> $\alpha$ </sup> where  $\alpha$  =0,1, 2 etc depicting variation of G as constant, linear and parabolic with depth respectively. However, many designers feel this could be unrealistic, especially for linear and parabolic variation as because it depicts G = 0 at the crest of dam.

Finally, none of the analytical methods takes care of the practical situation of impermeable clay core which is often deployed in an earth dam of large magnitude to control the seepage through it.

<sup>1</sup> Head of the Department, (Civil and Structural Engineering), Petrofac International Limited, Sharjah U.A.E. , Email Indrajit.Chowdary@petrofac.com

<sup>2</sup> Professor & Head, Department of Civil Engineering, Indian Institute of Technology, Kharagpur, Kharagpur 721 302,India, Email dasgupta@civil.iitkgp.ernet.in

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Present paper is thus an attempt to furnish a solution to number of such deficiencies as cited above and arrive at a more realistic solution.

## The Proposed Method

Shown in Figure 1 is a typical triangular shear beam usually considered for a conventional linear analysis of a homogeneous earth dam.



Fig. 1 Typical Triangular Shear Beam as Considered for Earth Dam

The equation of motion of such dams are usually expressed as

$$\frac{\partial^2 u}{\partial t^2} = \frac{G}{\rho} \left[ \frac{\partial^2 u}{\partial z^2} + \frac{1}{z} \frac{\partial u}{\partial z} \right]$$
(1)

in which, soil properties are: G = dynamic shear modulus;  $\rho$ = mass density ( $\gamma$ /g);  $\gamma$ = unit weight; and g = acceleration due to gravity; u = displacement amplitude of the soil in x-direction.

For the above type of earth dams, boundary conditions considered are

At z = 0,  $\partial u / \partial z$  = 0 for all values of t;

At z = H, u = 0 for all values of t.

Imposing the above boundary conditions, eqn. (1) may be written as

$$u(z,t) = \sum_{n=1}^{\infty} \left[ A_n \sin \omega_n t + B_n \cos \omega_n t \right] J_0(\beta_n z / H)$$
(2)

in which,  $A_n$  =  $B_n$  = constants that are functions of the initial conditions; J\_0= Bessel's function of first kind of order 0;  $\beta_n$  = a constant having values  $\beta_1$  = 2.404,  $\beta_2$  = 5.52  $\beta_3$  = 8.65 etc. (Jeffrey, 2005).

Based on above it may be stated that the generalized shape function of a triangular shear beam vibrating under its own inertia can be expressed as

$$N_{j} = J_{0} \left( \beta_{j} Z / H \right)$$
(3)

where j = 1, 2, 3, 4, ... are the number modes considered for analysis.

For a two dimensional plane strain body under deformation, the shear strain energy (Timoshenko & Young, 1982) may be expressed as

$$V = \frac{\nu G}{1 - 2\nu} \left( \varepsilon_x + \varepsilon_z \right)^2 + G \left( \varepsilon_x^2 + \varepsilon_z^2 \right) + \frac{G}{2} \left( \gamma_{xz}^2 \right)$$
(4)

in which, V = strain energy density; v = Poisson's ratio;  $\varepsilon_{x,\varepsilon_z}$  and  $\gamma_{xz}$  = strain in the body.

Considering  $u(x,z,t) = N_r(x,z).q(t)$  we have

$$\frac{\partial V}{\partial q_r} = \frac{2G(1-\nu)}{1-2\nu} \frac{\partial N_i}{\partial x} \frac{\partial N_r}{\partial x} q_i q_r + G \frac{\partial N_i}{\partial z} \frac{\partial N_r}{\partial z} q_i q_r$$
(5)

where, q(t) is exclusively a time function.

From the above, it can be shown (Hurty & Rubenstein, 1967) that for a body of height H and uniform width B, the stiffness and mass matrices can be expressed as

$$K_{ir} = \int_{0}^{HB} \int_{0}^{B} \left[ \frac{2G(1-\nu)}{1-2\nu} \frac{\partial N_i}{\partial x} \frac{\partial N_r}{\partial x} + G \frac{\partial N_i}{\partial z} \frac{\partial N_r}{\partial z} \right] dx dz$$
(6)  
and

$$\mathcal{A}_{ir} = \frac{\gamma}{g} \int_{0}^{H} \int_{0}^{B} N_i N_r dx dz$$
(7)

For shear waves propagating in the vertical direction, it has been shown by Chowdhury & Dasgupta (2007) that in one dimension, a soil body of depth H and extending to infinity in horizontal direction, eqns. (6) and (7) can be expressed as

$$\kappa_{ir} = \int_{0}^{H} \left[ G \frac{\partial N_{i}}{\partial z} \frac{\partial N_{r}}{\partial z} \right] dz$$
(8)

$$M_{ir} = \frac{\gamma}{g} \int_{0}^{H} N_{i} N_{r} dz$$
(9)



Fig. 2 A typical Trapezoidal Section of an Earth Dam

For a typical trapezoidal section of an earth dam shown in Figure 2, eqns. (8) and (9) can be modified and expressed as

$$K_{ir} = GA_{t} \int_{0}^{H} \left[ \left( 1 + \psi \frac{z}{H} \right) \frac{\partial N_{i}}{\partial z} \frac{\partial N_{r}}{\partial z} \right] dz$$
(10)

and

$$M_{ir} = \frac{\gamma A_t}{g} \int_0^H \left( 1 + \psi \frac{z}{H} \right) N_i N_r dz$$
(11)

where,  $A_t$  = cross sectional area of the dam at z = 0 and for 1.0m depth (perpendicular to the plane of the paper) is equal to B<sub>t</sub>;  $\psi$  is dimensionless constant expressed as  $\psi = (B_p - B_t) / B_t$ ;

N<sub>i</sub> and N<sub>r</sub> are expressed in eqn. (3).

Considering  $\xi = z / H$  when  $z \to 0$   $\xi \to 0$  and when  $z \to H$ ,  $\xi \to 1$ , eqns. (10) and (11) can be expanded and expressed for the first three modes as

$$\begin{bmatrix} \mathcal{K} \end{bmatrix} = \frac{GA_{t}}{H} \begin{vmatrix} \beta_{1} \beta_{2}^{-1} \int_{0}^{1} (1 + \psi\xi) J_{1}^{2}(\beta_{1}\xi) d\xi & \text{Symmetrical} \\ \beta_{1} \beta_{2} \int_{0}^{1} (1 + \psi\xi) J_{1}(\beta_{1}\xi) J_{1}(\beta_{2}\xi) d\xi & \beta_{2}^{-2} \int_{0}^{1} (1 + \psi\xi) J_{1}^{2}(\beta_{2}\xi) d\xi \\ \beta_{1} \beta_{3} \int_{0}^{1} (1 + \psi\xi) J_{1}(\beta_{1}\xi) J_{1}(\beta_{3}\xi) d\xi & \beta_{2} \beta_{3} \int_{0}^{1} (1 + \psi\xi) J_{1}(\beta_{2}\xi) J_{1}(\beta_{3}\xi) d\xi & \beta_{3}^{-2} \int_{0}^{1} (1 + \psi\xi) J_{1}^{2}(\beta_{3}\xi) d\xi \end{bmatrix}$$
(12)  
$$\begin{bmatrix} M \end{bmatrix} = \frac{\gamma A_{t} H}{g} \begin{bmatrix} \int_{0}^{1} (1 + \psi\xi) J_{0}^{2}(\beta_{1}\xi) d\xi & \text{Symmetrical} \\ \int_{0}^{1} (1 + \psi\xi) J_{0}(\beta_{1}\xi) J_{0}(\beta_{2}\xi) d\xi & \int_{0}^{1} (1 + \psi\xi) J_{0}^{2}(\beta_{2}\xi) d\xi \\ \int_{0}^{1} (1 + \psi\xi) J_{0}(\beta_{1}\xi) J_{0}(\beta_{3}\xi) d\xi & \int_{0}^{1} (1 + \psi\xi) J_{0}^{2}(\beta_{2}\xi) d\xi \end{bmatrix}$$
(13)

Eqns. (12) and (13) are generalized expression for stiffness and mass matrices for a trapezoidal dam shown in Figure 2, having G invariant with depth. Individual elements of [K] and [M] matrices are obtained by numerical integration of the respective terms between limits 0-1.

For the particular case of trapezoidal section is a triangle i.e. limit  $A_t \rightarrow 0$  and  $\psi \rightarrow \infty$ , eqns. (12) and (13) can be expressed as

$$\begin{bmatrix} \mathcal{K} \end{bmatrix} = \frac{GA_t}{H} \begin{bmatrix} 3.894 \times 10^6 & -736.854 & -6.425 \times 10^3 \\ -736.854 & 8.82 \times 10^6 & 1.582 \times 10^4 \\ -6.425 \times 10^3 & 1.582 \times 10^4 & 1.378 \times 10^7 \end{bmatrix}$$
(14)

And

$$\begin{bmatrix} M \end{bmatrix} = \frac{\gamma A_{t} H}{g} \begin{bmatrix} 6.742 \times 10^{5} & -156.128 & -18.743 \\ -156.128 & 2.895 \times 10^{5} & 207.419 \\ -18.473 & 207.419 & 1.844 \times 10^{5} \end{bmatrix}$$
(15)

Considering the eigen value problem of the above (Bathe, 1996) as

$$[K][\varphi] = \lambda[M][\varphi] \tag{16}$$

where  $\lambda$  and  $\phi$  are the eigen values and eigen vectors of matrix [K] and [M] respectively.

We have then

$$\begin{bmatrix} \lambda \end{bmatrix} = \begin{bmatrix} 5.775 & 0 & 0 \\ 0 & 30.469 & 0 \\ 0 & 0 & 74.758 \end{bmatrix} \frac{V_s^2}{H^2}$$
(17)

where  $V_{\rm s}=\sqrt{Gg/\gamma}$ , the shear wave velocity of soil.

Since 
$$\omega^2 = \lambda$$
, one can write  
 $\begin{bmatrix} \omega \end{bmatrix} = \begin{bmatrix} 2.403 & 0 & 0 \\ 0 & 5.52 & 0 \\ 0 & 0 & 8.646 \end{bmatrix} \frac{V_s}{H} \Rightarrow \begin{bmatrix} C_{\omega i} \end{bmatrix}_{H}^{V_s}$  (18)

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Table-1.

Table 1 Comparison of Con by Various Methods

| Mode | Mononobe | Makdisi<br>& Seed | Gazetas | Proposed |
|------|----------|-------------------|---------|----------|
| 1    | 2.409    | 2.4               | 2.404   | 2.403    |
| 2    | 5.521    | 5.52              | 5.52    | 5.52     |
| 3    | 8.654    | 8.65              | 8.654   | 8.646    |

It is observed that  $C_{\scriptscriptstyle\!\! \omega\iota}$  based on proposed method is in excellent agreement with established methods for limit  $A_t \rightarrow 0$ .

Having established the correctness of basic condition of derivation for the particular case of limit  $A_t \! \rightarrow \! 0$  , we present variance of time period of the dam for various values of  $\psi$ considering  $T=2\pi/\omega$ . This is given in Table-2. The time period is expressed as  $T_i = C_{Ti}(H/V_s)$ .

| for First Three Modes |       |                 |       |  |  |  |
|-----------------------|-------|-----------------|-------|--|--|--|
| ψ                     | CT1   | C <sub>T2</sub> | Стз   |  |  |  |
| 8                     | 2.615 | 1.138           | 0.727 |  |  |  |
| 99                    | 2.64  | 1.149           | 0.733 |  |  |  |
| 49                    | 2.666 | 1.159           | 0.739 |  |  |  |
| 24                    | 2.715 | 1.178           | 0.749 |  |  |  |
| 15                    | 2.763 | 1.193           | 0.756 |  |  |  |
| 12                    | 2.809 | 1.207           | 0.762 |  |  |  |
| 9                     | 2.854 | 1.219           | 0.766 |  |  |  |

Table 2 Variation of CT

It is observed that time periods gets elongated with increase in crest width though the variation for fundamental time period( which is most critical) is not much and is of the order of 9% only (from  $\psi \rightarrow \infty$  to 9). As such, the proposed method though more realistic, does not give any significant advantage over the established methods using triangular homogeneous sections. However, distinct advantage of the proposed method will emerge subsequently when we take up the case of dam with impermeable cores which is more a reality in field than a homogenous section assumed for dynamic analysis of such earth dams.

The first three mode shapes/ eigenvectors for the dam based on eqn. (3) are shown in Figure 3.



Fig. 3 Eigen Vectors for First Three Modes for the Dam

#### Effect of Variation of G with Depth

Gazetas (1982) derived solution of dynamic response of an earth dam considering  $G(z)=G(z/H)^{\alpha}$ . It is apparent from above that while it gives a G value constant with depth ( $\alpha$ =0), for linear and parabolic variation it gives G = 0 at the crest of the dam. Since this will invariably have a finite value we propose to consider G(z) as

$$G(z) = G(1 + z / H)^{\alpha}$$
<sup>(19)</sup>

The variation of  ${\rm G}$  for this type of curve is shown in Figure 4.



Fig. 4 Proposed Variation of G With Depth

For solution to this end, that has no established answers, eqn. (12) gets modified to

$$\begin{bmatrix} \mathcal{K} \end{bmatrix} = \frac{GA_{i}}{H} \begin{bmatrix} \beta_{1}^{2} \int_{0}^{1} (1+\xi)^{\alpha} (1+\psi\xi) J_{1}^{2}(\beta_{1}\xi) d\xi & \text{Symmetrical} \\ \beta_{1}\beta_{2} \int_{0}^{1} (1+\xi)^{\alpha} (1+\psi\xi) J_{1}(\beta_{1}\xi) J_{1}(\beta_{2}\xi) d\xi & \beta_{2}^{2} \int_{0}^{1} (1+\xi)^{\alpha} (1+\psi\xi) J_{1}^{2}(\beta_{2}\xi) d\xi \\ \beta_{1}\beta_{3} \int_{0}^{1} (1+\xi)^{\alpha} (1+\psi\xi) J_{1}(\beta_{1}\xi) J_{1}(\beta_{3}\xi) d\xi & \beta_{2}\beta_{3} \int_{0}^{1} (1+\xi)^{\alpha} (1+\psi\xi) J_{1}(\beta_{2}\xi) J_{1}(\beta_{3}\xi) d\xi & \beta_{3}^{2} \int_{0}^{1} (1+\xi)^{\alpha} (1+\psi\xi) J_{1}^{2}(\beta_{3}\xi) d\xi \end{bmatrix}$$
(20)

where  $\alpha = 1$  and 2 respectively for linear and parabolic variation.

Based on above variation of  $C_T$  for linear and parabolic profile for different values of  $\psi$  are as presented in Table-3.

Intermediate values can well be linearly interpolated considering the variation of  $C_T$  with respect to  $\psi$  is almost linear as shown in Figure 5.

Table 3 Values of  $C_T$  With Respect to Linear and Parabolic Variation of Soil for First Three Modes

|    | Lin   | Linear Variation |                 |       | Parabolic Variation |                 |  |
|----|-------|------------------|-----------------|-------|---------------------|-----------------|--|
| ψ  | CT1   | C <sub>T2</sub>  | C <sub>T3</sub> | CT1   | C <sub>T2</sub>     | C <sub>T3</sub> |  |
| 8  | 2.005 | 0.924            | 0.585           | 1.554 | 0.754               | 0.460           |  |
| 99 | 2.026 | 0.934            | 0.59            | 1.573 | 0.763               | 0.463           |  |
| 49 | 2.048 | 0.943            | 0.594           | 1.591 | 0.776               | 0.466           |  |
| 24 | 2.089 | 0.959            | 0.601           | 1.626 | 0.785               | 0.470           |  |
| 15 | 2.134 | 0.975            | 0.607           | 1.664 | 0.798               | 0.475           |  |
| 12 | 2.163 | 0.984            | 0.610           | 1.688 | 0.806               | 0.477           |  |
| 9  | 2.203 | 0.996            | 0.614           | 1.722 | 0.816               | 0.480           |  |



Fig. 6 An Earth Dam with Clay Core to Restrict the Seepage

The stiffness matrix for the dam section can be expressed as

$$\begin{bmatrix} \mathcal{K} \end{bmatrix} = \mathbf{G}\mathbf{A}_{t} \int_{0}^{H} \begin{bmatrix} \left(\mathbf{1} + \psi \frac{z}{H}\right) \frac{\partial N_{i}}{\partial z} \frac{\partial N_{r}}{\partial z} \end{bmatrix} dz - \mathbf{G}\mathbf{A}_{tc} \int_{0}^{H} \begin{bmatrix} \left(\mathbf{1} + \psi_{c} \frac{z}{H}\right) \frac{\partial N_{i}}{\partial z} \frac{\partial N_{r}}{\partial z} \end{bmatrix} dz + \mathbf{G}_{c}\mathbf{A}_{tc} \int_{0}^{H} \begin{bmatrix} \left(\mathbf{1} + \psi_{c} \frac{z}{H}\right) \frac{\partial N_{i}}{\partial z} \frac{\partial N_{r}}{\partial z} \end{bmatrix} dz$$
(22)

$$\Rightarrow \left[K\right] = GA_{t} \int_{0}^{H} \left[ \left(1 + \psi \frac{z}{H}\right) \frac{\partial N_{t}}{\partial z} \frac{\partial N_{r}}{\partial z} + \left(m - 1\right) \left(\frac{A_{tc}}{A_{t}}\right) \int_{0}^{H} \left(1 + \psi_{c} \frac{z}{H}\right) \frac{\partial N_{t}}{\partial z} \frac{\partial N_{r}}{\partial z} \right] dz$$
(23)

in which, G<sub>c</sub>= dynamic shear modulus of clay core and let m = G<sub>c</sub>/G the modular ratio of clay core and outer material, A<sub>tc</sub> is area of inner core at the crest of dam @  $B_{tc} \times 1$ .

Substituting eqn. (3), eqn. (23) can be expanded for the first three modes as,

$$\begin{bmatrix} K \end{bmatrix} = \begin{bmatrix} k_{11} & \text{Symm.} \\ k_{12} & k_{22} \\ k_{13} & k_{32} & k_{33} \end{bmatrix}$$
(24)

where,

$$k_{11} = \frac{GA_{t}}{H} \left[ \int_{0}^{1} (1 + \psi\xi) \beta_{1}^{2} J_{1}^{2} (\beta_{1}\xi) + (m - 1) \left( \frac{A_{tc}}{A_{t}} \right) \int_{0}^{1} (1 + \psi_{c}\xi) \beta_{1}^{2} J_{1}^{2} (\beta_{1}\xi) \right] d\xi$$
(25)



 $(B_{b}-B_{t}) / B_{t}$ 

Fig. 5 Variation of Factor C<sub>T1</sub> for Linear and Parabolic Distribution of Soil

It is again observed here that while the variation in time period is about 25% for linear variation of G, with respect to G constant with depth, the variation due to tapering of the section is of the order of 10% only.

Effect of Inner Core on Dynamic Response of the Dam

No analytical methods exist till date for this case in terms of dynamic response. It is in such a situation one resorts to the finite element method (FEM) for a comprehensive analysis. However, considering the dynamic response remaining linear, the problem can be approached as given hereunder.

Shown in Figure 6 is a typical earth dam with an internal clay core. Let width of the core at crest be  $B_{tc}$ , and  $B_{bc}$  be the width at bottom. Here suffix c denotes clay core.

Maintaining mathematical similarity let us define,

$$\psi_{\rm c} = \left(B_{\rm bc} - B_{\rm tc}\right) / B_{\rm tc} \tag{21}$$

$$k_{12} = \frac{GA_{t}}{H} \left[ \int_{0}^{1} (1 + \psi\xi) \beta_{1}\beta_{2}J_{1}(\beta_{1}\xi) J_{1}(\beta_{2}\xi) + (m-1) \left( \frac{A_{tc}}{A_{t}} \right) \int_{0}^{1} (1 + \psi_{c}\xi) \beta_{1}\beta_{2}J_{1}(\beta_{1}\xi) J_{1}(\beta_{2}\xi) \right] d\xi$$
(26)

$$k_{13} = \frac{GA_t}{H} \left[ \int_0^1 (1 + \psi\xi) \beta_1 \beta_3 J_1(\beta_1\xi) J_1(\beta_3\xi) + (m-1) \left( \frac{A_{tc}}{A_t} \right) \int_0^1 (1 + \psi_c\xi) \beta_1 \beta_3 J_1(\beta_1\xi) J_1(\beta_3\xi) \right] d\xi$$
(27)

$$k_{22} = \frac{GA_{t}}{H} \left[ \int_{0}^{1} (1 + \psi\xi) \beta_{2}^{2} J_{1}^{2} (\beta_{2}\xi) + (m - 1) \left( \frac{A_{tc}}{A_{t}} \right) \int_{0}^{1} (1 + \psi_{c}\xi) \beta_{2}^{2} J_{1}^{2} (\beta_{2}\xi) \right] d\xi$$
(28)

$$k_{23} = \frac{GA_t}{H} \left[ \int_0^1 (1 + \psi\xi) \beta_3 \beta_2 J_1(\beta_3 \xi) J_1(\beta_2 \xi) + (m - 1) \left( \frac{A_{tc}}{A_t} \right) \int_0^1 (1 + \psi_c \xi) \beta_3 \beta_2 J_1(\beta_3 \xi) J_1(\beta_2 \xi) \right] d\xi$$
(29)

$$k_{33} = \frac{GA_t}{H} \left[ \int_0^1 (1 + \psi\xi) \beta_3^2 J_1^2 (\beta_3\xi) + (m - 1) \left( \frac{A_{tc}}{A_t} \right) \int_0^1 (1 + \psi_c\xi) \beta_3^2 J_1^2 (\beta_3\xi) \right] d\xi$$
(30)

Similarly the mass matrix is given by the expression

$$\begin{bmatrix} M \end{bmatrix} = \begin{bmatrix} m_{11} & \text{Symmetrical} \\ m_{12} & m_{22} \\ m_{13} & m_{23} & m_{33} \end{bmatrix}$$
(31)

Considering p = $\gamma_c/\gamma$  the unit weight ratio of core soil and the outer soil, mass matrix coefficients can be expressed as

$$m_{11} = \frac{\gamma A_t H}{g} \int_{0}^{1} \left[ (1 + \psi \xi) J_0^2 (\beta_1 \xi) + (p - 1) \left( \frac{A_{tc}}{A_t} \right) (1 + \psi_c \xi) J_0^2 (\beta_1 \xi) \right] d\xi$$
(32)

$$m_{12} = \frac{\gamma A_t H}{g} \int_0^1 \left[ (1 + \psi \xi) J_0(\beta_1 \xi) J_0(\beta_2 \xi) + (p - 1) \left( \frac{A_{tc}}{A_t} \right) (1 + \psi_o \xi) J_0(\beta_1 \xi) J_0(\beta_2 \xi) \right] d\xi$$
(33)

$$m_{13} = \frac{\gamma A_t H}{g} \int_0^1 \left[ (1 + \psi\xi) J_0(\beta_1\xi) J_0(\beta_3\xi) + (p-1) \left( \frac{A_{tc}}{A_t} \right) (1 + \psi_0\xi) J_0(\beta_1\xi) J_0(\beta_3\xi) \right] d\xi$$
(34)

$$m_{22} = \frac{\gamma A_t H}{g} \int_{0}^{1} \left[ (1 + \psi \xi) J_0^2 (\beta_2 \xi) + (p - 1) \left( \frac{A_{tc}}{A_t} \right) (1 + \psi_c \xi) J_0^2 (\beta_2 \xi) \right] d\xi$$
(35)

$$m_{23} = \frac{\gamma A_t H}{g} \int_0^1 \left[ (1 + \psi \xi) J_0(\beta_2 \xi) J_0(\beta_3 \xi) + (p - 1) \left( \frac{A_{tc}}{A_t} \right) (1 + \psi_c \xi) J_0(\beta_2 \xi) J_0(\beta_3 \xi) \right] d\xi$$
(36)

$$m_{33} = \frac{\gamma A_t H}{g} \int_{0}^{1} \left[ (1 + \psi \xi) J_0^2 (\beta_3 \xi) + (p - 1) \left( \frac{A_{tc}}{A_t} \right) (1 + \psi_c \xi) J_0^2 (\beta_3 \xi) \right] d\xi$$
(37)

Once the stiffness and mass matrices are obtained based on above formulation one can follow eqn. (16) for standard eigen value solution of the problem to derive the time periods and vibration modes. Stiffness coefficients derived through eqns. (25) to (30) is based on soil having G constant with depth. However, considering generality of the solution it is not difficult to incorporate the variation of G with depth. For instance if we have a case where the outer shell has a soil that varies linearly with depth while inner core has stiff clay whose dynamic shear modulus is constant with depth the stiffness matrix gets modified as follows.

$$k_{11} = \frac{GA_{t}}{H} \left[ \int_{0}^{1} (1 + \psi\xi) (1 + \xi) \beta_{1}^{2} J_{1}^{2} (\beta_{1}\xi) + (m - 1) \left( \frac{A_{tc}}{A_{t}} \right) \int_{0}^{1} (1 + \psi_{c}\xi) \beta_{1}^{2} J_{1}^{2} (\beta_{1}\xi) \right] d\xi$$
(38)

and so on.

It is apparent from above that where established methods do not provide an answer to this problem in terms of *propagation of waves through a homogeneous shear beam of varying cross section,* the proposed method comes up with a rational solution of this practical problem.

#### **Estimation of Dynamic Amplitude and Stress**

For a body subjected to earthquake force, maximum amplitude is expressed as (Clough & Penzien, 1982)

$$S_{d} = S_{a} / \omega^{2}$$
(39)

In terms of provision as furnished in IS code, eqn. (39) can be finally expressed as

$$S_{di} = \kappa_i \left(\frac{ZI}{2R}\right) \frac{S_{ai}}{\omega^2}$$
(40)

where, Z = zone factor; I = importance factor; R= ductility factor and,  $\kappa_{I}$  = modal mass participation factor

usually expressed as  $\sum_{i=1}^{n} m_i \phi_i \Big/ \sum_{i=1}^{n} m_i \phi_i^2$  .

It is to be noted that IS 1893(2002) [draft code for earthen dam] does not have any provision for R the ductility factor in terms of earthen dam , though it implicitly assumes a value of R=1.5 in a semi empirical approach proposed there in. However, it has been shown by (Chowdhury & Dasgupta 2007) that R=2 to 3 will mostly give a reasonable result. Surely, more research is needed to define this value with more clarity for earth dams.

The modal mass participation factor based on above formulation can be expressed in this case as

$$\kappa_{i} = \int_{0}^{1} (1 + \psi\xi) J_{0}(\beta_{i}\xi) / \int_{0}^{1} (1 + \psi\xi) J_{0}(\beta_{i}\xi)^{2}$$
(41)

It is observed here that instead of a unique value as expressed by Makdisi & Seed (1977) modal participation factor is a function of the top and bottom width in terms of  $\psi$ . Different values of  $\kappa_i$  with respect to  $\psi$  are furnished hereafter in Table- 4.

| Table 4 Variation of                 |   |
|--------------------------------------|---|
| Modal Participation Factor KI with V | Y |

| ψ        | $\kappa_1$ | κ <sub>2</sub> | κ <sub>3</sub> |
|----------|------------|----------------|----------------|
| $\infty$ | 1.602      | -1.065         | 0.851          |
| 99       | 1.591      | -1.00          | 0.85           |
| 49       | 1.581      | -0.94          | 0.849          |
| 24       | 1.562      | -0.827         | 0.847          |
| 15       | 1.543      | -0.718         | 0.845          |
| 12       | 1.532      | -0.655         | 0.844          |
| 9        | 1.515      | -0.561         | 0.843          |
|          |            |                |                |

It will be observed from the table that modal participation factor varies significantly especially for the second mode with respect to the top and bottom width of the dam. The value of  $\kappa_i$  as obtained for  $\psi \rightarrow \infty$  matches exactly the value as proposed by Makdisi & Seed (1977).

The displacement of the dam over the height H can be thus expressed as

$$u_{i}(z,t) = \kappa_{i} \left(\frac{ZI}{2R}\right) \frac{S_{ai}}{\omega_{i}^{2}} J_{0} \left(\beta_{i} \frac{Z}{H}\right)$$
(42)

Substituting  $T = 2\pi/\omega$ , eqn. (42) after some simplification, can be expressed as

$$u_{i}(z,t) = \kappa_{i} \left(\frac{ZI}{2R}\right) \frac{C_{\tau_{i}}^{2} \gamma H^{2}}{4\pi^{2} G} \left(\frac{S_{ai}}{g}\right) J_{0} \left(\beta_{i} \frac{z}{H}\right)$$
(43)

The shear strain is expressed as

$$\gamma_{xzi} = \frac{\partial u}{\partial z} = \kappa_i \left(\frac{ZI}{2R}\right) \frac{C_{\tau i}^2 \beta_i \gamma H}{4\pi^2 G} \left(\frac{S_{ai}}{g}\right) J_1 \left(\beta_i \frac{z}{H}\right)$$
(44)

The shear stress that varies along the depth is finally expressed as

$$\tau_{xzi} = \kappa_i \left(\frac{ZI}{2R}\right) \frac{C_{Ti}^2 \beta_i \gamma H}{4\pi^2} \left(\frac{S_{ai}}{g}\right) J_1\left(\beta_i \frac{Z}{H}\right)$$
(45)

# Earthquake Stability and Estimation of Lateral Seismic Coefficient ( $\alpha_h$ )

Estimation of lateral stability of earthen dams under earthquake is still marred by some uncertainties, and a number of theories have been proposed e.g.

- Slip Circle analysis based on pseudo static method.
- > Sliding block method
- > Dynamic finite element analysis.

Of all the above methods, slip circle method based on pseudo static analysis is most popular though it has been shown that the method can at times gives unsatisfactory results. Terzaghi (1950) who first proposed it for stability of embankments under earthquake conceded the method to be crude, while Seed (1979) showed a number of dams in USA that had undergone failure in earthquake, had a factor of safety (FOS) greater than 1.0 based on pseudo static analysis.

Newmark (1965) proposed a sliding block technique, though found to be theoretically sound, essentially requires time history response of a site which is always not available. Moreover the movement of failed mass as a rigid block may not be always realistic when the soil is not reasonably stiff.

Dynamic finite element analysis (Chopra &

Clough 1966, Duncan 1992) though gives the most comprehensive result, requires significant engineering effort and very careful evaluation of in-situ soil parameters of dam which is surely an expensive exercise and can possibly be justified only for very large dam of utmost importance.

Thus, in-spite of its limitation, pseudo static analysis based on slip circle method because of its simplicity in application continues to be the most popular method in practice where the earthquake force is simulated by an equivalent lateral seismic coefficient  $\alpha_h$  (Figure 2).

One major difficulty and limitation that arises in estimation of  $\alpha_h$  for dams is that unlike a normal structure, where the lateral seismic coefficient can be considered as constant over the height of a structure, an earth dam is a far more flexible system and as such  $\alpha_h$  varies with height. Hence in many cases what would be the effective lateral seismic coefficient becomes a matter of judgment.

As per IS-1893(2002) [draft code for earthen dam], for instance,  $\alpha_{\text{h}}$  is expressed by an empirical formula of

$$\alpha_h = \frac{1}{3} \times Z \times I \times S \tag{46}$$

where Z and I are as explained earlier and S is soil factor that varies from max 2.0 for soft soil to 1.0 minimum.

The peak horizontal ground acceleration (PHGA) is considered as  $a_{\max}=Z\times I\times S$ , while the net lateral force due to earthquake is given by

$$F = \frac{1}{3} \times Z \times I \times S \times W \tag{47}$$

It is obvious that irrespective of the time period of the dam this value remains constant for a particular zone( II, III, IV etc) though it is well known that how much acceleration a body is subjected to is dependent on time periods of the body in different modes.

Since value of  $\alpha_h$  proposed is empirical in nature, there could be cases when response could be overestimated and vice versa and matching with above mentioned codal provision vide Equation (47) can just be a coincidence.

Based on the proposed dynamic theory, lateral coefficient  $\alpha_h$  can be estimated as mentioned hereafter. Typical slope failure profile of an earth dam, based on wedge theory, is shown in Figure 7.

Following Makdisi & Seed (1977), the total horizontal force acting on this wedge is expressed as

$$F(z,t) =$$
 Mass of triangular wedge  $\times \ddot{u}_{av}$  (48)

were  $\ddot{u}_{av}$  = average acceleration over the dam height.

Based on Figure 7, eqn. (48) can be expressed as

$$\ddot{u}_{av} = \frac{2F(z,t)g}{B_z \times z \times \gamma} = \frac{2\tau_{xz}g}{z\gamma}$$
(49)

or, 
$$\alpha_{hi} = \frac{\ddot{u}_{av}}{g} = \frac{2\tau_{xzi}}{z\gamma} =$$
  
 $2\kappa_i \left(\frac{ZI}{2R}\right) \frac{C_{\tau i}^2 \beta_i H}{4\pi^2 z} \left(\frac{S_{ai}}{g}\right) J_1\left(\beta_i \frac{z}{H}\right)$  (50)

where i =1,2,3,....is the number of modes.

It is evident from eqn. (50) that  $\alpha_h$  is a function of the depth z and shape function as described in eqn. (3).

Now let as assume that this lateral seismic coefficient is effective over the whole cross section of dam.

Thus over full height H of the dam, combining eqns. (50) and (11), we have

$$F_{ei} = \alpha_{hi}W = 2\kappa_i \left(\frac{ZI}{2R}\right) \frac{C_{Ti}^2 \beta_i H \gamma A_t}{4\pi^2} \left(\frac{S_{ai}}{g}\right)_0^H \frac{1}{z} \left(1 + \psi \frac{z}{H}\right) J_1\left(\beta_i \frac{z}{H}\right) dz$$
(51)

where

$$W = \gamma A_t \int_0^1 (1 + \psi \frac{z}{H}) dz$$
(52)

Thus average lateral seismic coefficient over the full height of the dam can be expressed as

$$\alpha_{hi} = \frac{\Gamma_{ei}}{W} = \frac{2\kappa_i \left(\frac{ZI}{2R}\right) \frac{C_{\tau i}^2 \beta_i}{4\pi^2} \left(\frac{S_{ai}}{g}\right)_0^1 \frac{1}{\xi} (1 + \psi\xi) J_1(\beta_i\xi) d\xi}{\int_0^1 (1 + \psi\xi) d\xi}$$
(53)



Fig.7 Assumed Failure Profile of an Earth Dam

It may be observed that  $\alpha_{\text{hi}}$  obtained using eqn. (53) as expected is a dimensionless quantity.

Eqn. (53) can be further simplified to

$$\alpha_{hi} = \operatorname{Coeff}_{i} \times \left(\frac{ZI}{2R}\right) \left(\frac{S_{ai}}{g}\right)$$
(54)

where, Coeffi

$$= \left[2\kappa_i \frac{C_{\tau_i}^2 \beta_i}{4\pi^2} \int_0^1 \frac{1}{\xi} (1+\psi\xi) J_1(\beta_i\xi) d\xi\right] / \int_0^1 (1+\psi\xi) d\xi \quad (55)$$

Values of the coefficient in eqn. (55) for various values of  $\psi$  are furnished in Table-5.

The design lateral coefficient based on eqn. (54) can finally be considered for first three modes as

$$\alpha_{hr} = \sqrt{\alpha_{h1}^{2} + \alpha_{h2}^{2} + \alpha_{h3}^{2}}$$
(56)

#### Table 5 Values of Seismic Coefficient (coeffi) for Different Values of $\psi$ , for the First Three Modes

|    | G constant with depth |      | G lin | G linear with depth |       | G parabolic with depth |      |      |      |
|----|-----------------------|------|-------|---------------------|-------|------------------------|------|------|------|
| Ψ  | Modes                 |      | Modes |                     | Modes |                        |      |      |      |
|    | 1st                   | 2nd  | 3rd   | 1st                 | 2nd   | 3rd                    | 1st  | 2nd  | 3rd  |
| 8  | 1.11                  | 0.14 | 0.05  | 0.65                | 0.09  | 0.03                   | 0.39 | 0.06 | 0.02 |
| 99 | 1.13                  | 0.14 | 0.05  | 0.66                | 0.09  | 0.03                   | 0.40 | 0.06 | 0.02 |
| 49 | 1.14                  | 0.14 | 0.05  | 0.68                | 0.09  | 0.03                   | 0.41 | 0.06 | 0.02 |
| 24 | 1.18                  | 0.14 | 0.06  | 0.70                | 0.09  | 0.04                   | 0.42 | 0.06 | 0.02 |
| 15 | 1.21                  | 0.14 | 0.07  | 0.72                | 0.09  | 0.04                   | 0.44 | 0.06 | 0.03 |
| 9  | 1.26                  | 0.14 | 0.08  | 0.74                | 0.09  | 0.05                   | 0.45 | 0.06 | 0.03 |

#### Stability Analysis of Dam

As mentioned earlier the most popular method for stability analysis of dams under static load is based on slip circle methods like Swedish slip circle method, Bishops simplified analysis, etc. That soil fails along an arc was observed in a number of land slides in Alps from where Fellenius (1936) originally developed the method. In spite of its sound scientific background it has been observed to overestimate FOS under an actual earthquake Seed( 1979). One of the possible reasons for this could be that for a homogenous isotropic medium under transient dynamic load the failure surface could be different from a circular arc as assumed under static load.

Without going into detailed discussion, it can be argued that under a transient shock if a body fails, the failure profile would follow the path of least resistance. Since resisting force within soil body is developed by friction and cohesion in a particular plane it is apparent that for least resistance this surface should be a minimum. In other words it should be a straight line rather than a circular arc. Failure of dams along a straight line path is not uncommon and Whitman & Lambe (1979) points out that a number of dams resting on firm ground have been observed to undergo failure along a straight line even under static loads. Since most of the earthen dams are built on relatively firm ground it would thus not be illogical to assume a straight line failure profile of a dam surface under an earthquake. Finally under earthquake a number of frames which are essentially treated as shear frames the infill panels have been observed to undergo cracks that follow a straight line rather than a circular arc (Agarwal & Shrikhande 2004). Similarly deep beams and squat shear walls (where shear strain energy dominates) failing under earthquake has been observed to follow more or less a straight line (Park & Pauley 1980).

Based on above logic we propose to evaluate the dynamic stability of the dam as mentioned hereunder.

Shown in Figure 8 is an earth dam subjected to lateral earthquake force. It is evident that we can draw infinite number of planes having an angle  $\theta$  that can vary from 0 to angle  $\alpha$  (the slope of the dam) through which the dam can potentially slide. Among all these planes there exists one unique plane at an angle  $\theta$  which is the weakest and has the maximum probability of failure along that plane. In other words FOS against failure on this plane is a minimum.



Fig. 8 An Earth Dam with Various Failure Planes

Shown in Figure 9 is an earth dam section where the critical failure profile plane is at an angle  $\theta$  with the horizontal.

Based on geometry it can then be shown that area of triangle PQR ( $\Delta$ ) is given by

$$\Delta = \frac{1}{2} B_b^2 \frac{\sin\alpha \sin\theta}{\sin(\alpha + \theta)}$$
(57)

Thus weight of the dam above failure plane PQ can be expressed as

$$W_{cr} = \frac{\gamma}{2} \left[ \left( B_b + B_t \right) H - B_b^2 \frac{\sin \alpha \sin \theta}{\sin(\alpha + \theta)} \right]$$
(58)

Weight  $W_{\mbox{\tiny cr}}$  is then expected to slide down the plane PQ which is the critical plane of failure.

As shown in Figure 10, the weight  $W_{cr}$  slides down a critical plane at an angle  $\theta$  with horizontal.

The resistive force R may be expressed as

$$R = \mu N + c \times PQ \tag{59}$$

where,  $\mu$ = Angle of internal friction of soil usually expressed as tan  $\phi$ ; c = cohesion of soil, and PQ= length of the failure plane = B<sub>b</sub>[sin  $\alpha$  / sin( $\alpha$  +  $\theta$ )].

From free body diagram one can write

$$N = W_{cr}(\cos\theta - \alpha_{h}\sin\theta) \tag{60}$$

The force which drives the body down, is given by,  $F_p = W_{cr}(\sin\theta + \alpha_p \cos\theta)$ .

The resisting force is thus given by

$$F_{R} = \mu W_{cr}(\cos\theta - \alpha_{h}\sin\theta) + c \times B_{b} \frac{\sin\alpha}{\sin(\alpha + \theta)}$$
(61)

The factor of safety (FOS) is then expressed as

$$FOS = \frac{F_R}{F_D} = \frac{\mu (\cos\theta - \alpha_h \sin\theta) + \frac{cB_b}{W_{cr}} \frac{\sin\alpha}{\sin(\alpha + \theta)}}{\sin\theta + \alpha_b \cos\theta}$$
(62)

where  $W_{cr}$  is the weight expressed by eqn. (58).

To determine minimum factor of safety (FOS) one can now vary  $\theta$  from 0 to  $\alpha$  at an increment of ,say, 1 degree and evaluate the plane which is critical and FOS is minimum.

### Effect of Vertical Seismic Coefficient $\alpha_v$ on FOS

Normal perception is that vertical component of an earthquake has no effect on overall stability of dam. Though Mononobe (1924) showed that, a combination of horizontal and vertical acceleration led to severe damage in earth retaining structures in Kanto earthquake in Japan as early as 1920. Chopra (1966)



Fig. 9 A Typical Trapezoidal Section of an Earth Dam with its Failure Plane





through Finite Element Analysis showed vertical acceleration affects seismic response of earth dams. Ling & Mohri (1997) did an extensive study of this effect on earth dams and strongly advocates its consideration for estimating the stability. As per IS-1893 (2002),  $\alpha_v$  is usually considered as 0.5 of  $\alpha_h$ . This can then be incorporated in eqn. (62) as follows

$$FOS = \frac{\mu((1 \pm \alpha_v)\cos\theta - \alpha_h\sin\theta) + \frac{cB_b}{W_{cr}}\frac{\sin\alpha}{\sin(\alpha + \theta)}}{(1 \pm \alpha_v)\sin\theta + \alpha_h\cos\theta} \quad (63)$$

#### Stability of Dam with Impermeable Core

Stability of dam including the impermeable core induces significant computational difficulties. Firstly due to heterogeneity of the medium, shear stress changes between outer and inner shell material. Moreover, as there is a significant variation in stiffness between the outer and inner core material, distribution of forces between the two parts also varies. Usual practice is to use FEM for estimation of stability, where uncertainties prevail for if the meshing of the soil material is not sufficiently refined can provide upper bound results.

The problem is approached as given hereafter.

Normally the core constitute of stiff compacted silty clay/clayey silt (little friction is preferable for it significantly enhances shear strength with depth along with cohesion c) having minimum void ratio to reduce seepage. From strength point of view also they are usually stiffer than the outer shell material by about 3 to 4 times. Thus, if one looks at the overall response of the heterogeneous earth dam under earthquake, it can be concluded that the system acts analogous to a shear wall framed structure where the inner core acts as a stiff shear wall and outer shell acts like a connected frame. In other words distribution of the lateral force among outer and inner shell material is dependent on the relative stiffness of these two materials.

For a homogeneous isotropic body of area A and height H, static stiffness of soil is simply expressed as

$$K_{\rm st} = {\rm GA} / H \tag{64}$$

For earth dam with variable cross section having clay core eqn. (64) can be expressed as

$$\begin{aligned} 
\mathcal{K}_{st} &= \frac{\mathbf{G}\mathbf{A}_{t}}{H} \int_{0}^{1} (\mathbf{1} + \psi\xi) d\xi - \frac{\mathbf{G}\mathbf{A}_{tc}}{H} \int_{0}^{1} (\mathbf{1} + \psi_{c}\xi) d\xi \\ 
&+ \frac{\mathbf{G}_{c}\mathbf{A}_{tc}}{H} \int_{0}^{1} (\mathbf{1} + \psi_{c}\xi) d\xi \end{aligned}$$
(65)

On simplification, eqn. (65) can be expressed as

$$K_{\rm st} = \frac{GA_t}{H} \left[ \left( 1 + \frac{\psi}{2} \right) + \left( m - 1 \right) r_{\rm c} \left( 1 + \frac{\psi_{\rm c}}{2} \right) \right]$$
(66)

where  $m=G_c/G$  and  $r_c = A_{tc}/A_t$ .

as

The stiffness of the inner core may be expressed

$$K_{c} = \frac{G_{c}A_{tc}}{H} \left(1 + \frac{\psi_{c}}{2}\right)$$
(67)

Thus, if  $\alpha_h W$  is the total force on the dam, force resisted by inner core is given by

$$F_{hc} = \frac{K_c}{K_{st}} (\alpha_h W)$$
  
$$\Rightarrow F_{hc} = \left[ \frac{mr_c \left(1 + \frac{\psi_c}{2}\right)}{1 + \frac{\psi}{2} + (m - 1)r_c \left(1 + \frac{\psi_c}{2}\right)} \right] (\alpha_h W)$$
(68)

$$\Rightarrow F_{hc} = (\alpha_{hc}W) \text{ where}$$

$$\alpha_{hc} = \alpha_{h} \left[ \frac{mr_{c} \left(1 + \frac{\psi_{c}}{2}\right)}{1 + \frac{\psi}{2} + (m-1)r_{c} \left(1 + \frac{\psi_{c}}{2}\right)} \right]$$
(69)

Proceeding in identical manner it can be shown that the force induced in outer shell can be expressed as

$$F_{hS} = \left(\frac{\alpha_{h}W}{2}\right) \left[\frac{1 + \frac{\psi}{2} - r_{c}\left(1 + \frac{\psi_{c}}{2}\right)}{1 + \frac{\psi}{2} + (m - 1)r_{c}\left(1 + \frac{\psi_{c}}{2}\right)}\right]$$
(70)

Eqn. (70) can be rewritten as

$$F_{hS} = \alpha'_{hS}W$$

where,

$$\alpha_{\mathbf{b}}' = \frac{\alpha_{h}}{2} \left[ \frac{1 + \frac{\psi}{2} - r_{c} \left(1 + \frac{\psi_{c}}{2}\right)}{1 + \frac{\psi}{2} + (m - 1)r_{c} \left(1 + \frac{\psi_{c}}{2}\right)} \right]$$
(71)

Here the term  $\frac{1}{2}$  comes because of the fact that outer shell constitutes of two parts, and as such the total force on outer shell is thus divided equally into two sections (provided of course the outer shell is symmetric to the core).

Based on time period obtained from eqns. (24) and (31), the seismic lateral force coefficient  $\alpha_h$  is obtained using eqn. (56).

For a composite dam the total weight  ${\rm W}$  is expressed as

$$W = \gamma A_t H \left[ 1 + \frac{\psi}{2} + r_c \left( p - 1 \right) \left( 1 + \frac{\psi_c}{2} \right) \right]$$
(72)



with Clay Core to Restrict the Seepage

For calculation of FOS let us consider Figure 11.

It is evident that there can be two failures within the dam section:

1) Slope failure of the outer shell at a critical angle  $\theta$  (the PQ plane).

2) Shearing off of the inner core due to the force  $F_{hc}, vide \; eqn.\; (68).$ 

Proceeding in the same line as explained earlier if  $\theta$  be the critical plane at which the FOS is minimum,

Based on Figure 11, the weight of soil,  $W_{\text{b}}$  below the critical PQ plane is expressed as

$$W_{b} = \frac{\gamma (B_{b} - B_{bc})^{2}}{8} \frac{\sin\theta \sin\delta}{\sin(\delta - \theta)}$$
(73)

The gross weight of one outer shell is given by

$$W_{s} = \frac{\gamma H}{2} \left[ B_{bs} + B_{ts} \right]$$
(74)

#### where Bbs=0.5(Bb-Bbc) and Bts=0.5(Bt-Btc)

Subtracting eqn. (73) from eqn. (74), we get the critical weight  $W_{\rm cr}$  that slides along plane PQ.

The factor of safety for outer shell is now expressed as

$$FOS = \frac{\mu\left(\left(1 \pm \alpha_{v}'\right)\cos\theta - \alpha_{h}'\sin\theta\right) + \frac{c(B_{b} - B_{bc})}{2W_{cr}}\frac{\sin\delta}{\sin(\delta - \theta)}}{\left(1 \pm \alpha_{v}'\right)\sin\theta + \alpha_{h}'\cos\theta}$$
(75)

where  $\alpha'_{\text{hs}}$  is as expressed by eqn. (71) and  $\alpha'_{\nu}$  is 0.5 times  $\alpha'_{\text{hs.}}$ 

To arrive at minimum FOS we now vary  $\theta$  from 0 to  $\alpha$  at some predefined increment of say 1 degree to obtain the minimum value.

For inner core, force  $F_{\rm hc}$  as per eqn. (68) basically acts as the base shear like in a continuous shear wall. Then, this can be distributed over full height of the dam as

$$Q_i = F_{hc} \frac{W_i \times h_i}{\sum W_i \times h_i^2}$$
(76)

where

 $W_i$ = Weight of core at a particular depth  $h_i$  given

by  $\gamma_c A_t (1 + \psi_c \frac{Z_i}{H}) (z_i - z_{i-1})$ ; Q<sub>i</sub>= Nodal force at depth h<sub>i</sub>.

Summing up of all these nodal forces  $Q_{\rm i}$  up to a particular depth  $h_{\rm i}$  gives the shear force acting at that particular level. Thus,

$$V_{i(z=hi)} = \sum_{0}^{h_i} Q_i \tag{77}$$

The shear stress developed at any section is given by

$$\tau_{zi} = \frac{V_{zi}}{B_{tc} \left(1 + \psi_c \frac{Z}{H}\right) \times 1} \le c + \gamma_c \times Z \tan \varphi_c$$
(78)

where  $c + \gamma_c \times z \tan \varphi_c$  is the allowable shear stress at a particular depth z from crest and c is cohesion of soil in core and  $\phi_c$  is its internal angle of friction.

#### Effect of Hydrodynamic Pressure on Stability

Hydrodynamic pressure on the dam will be most critical when it creates a suction pressure on sloped surface.

It has been shown by Chowdhury & Dasgupta (2008) that hydrodynamic pressure due to earthquake

on a vertical surface for a fluid medium extending to infinity can be expressed as

$$p = \frac{12}{\pi(\pi+2)} \frac{S_a \gamma_w H_w}{g} \sin \frac{\pi z}{2H_w}$$
(79)

in which,  $H_w$ = vertical height of water in dam;  $S_{aw}$ = acceleration corresponding to free field time period of the water expressed as  $4H_w/v_w$ ;  $v_w$  = velocity of sound in water @ 1149 m/sec, and  $\gamma_w$ = unit weight of water.

Thus for a surface at an inclination  $\alpha$  the pressure normal  $(p_{\text{n}})$  to the surface can be expressed as

$$p_n = \frac{12}{\pi(\pi + 2)} \frac{S_{aw} \gamma_w H_w}{g} \sin \frac{\pi z}{2H_w} \sin \alpha$$
(80)

Thus the suction force  $V_{\mbox{\scriptsize w}}$  which reduces the normal force N is given by

$$V_{w} = \int_{0}^{H_{w}} p_{n} dz = 0.473 \frac{\gamma_{w} S_{aw} H_{w}^{2}}{g} \sin \alpha$$
 (81)

The factor of safety against stability considering the suction effect of hydrodynamic pressure can then be expressed as

$$FOS = \frac{\mu \left( \left( 1 \pm \alpha_v \right) \cos \theta - \alpha_h \sin \theta - \frac{V_w}{W_{cr}} \right) + \frac{cB_b}{W_{cr}} \frac{\sin \alpha}{\sin(\alpha + \theta)}}{\left( 1 \pm \alpha_v \right) \sin \theta + \alpha_h \cos \theta}$$
(82)

For clay core dam replace  $\alpha_v$  and  $\alpha_h$  by  $\alpha'_{vs}$  and  $\alpha'_{hs}$  respectively and shall affect the outer shell material only.

# **Results and Discussions**

To compare the results, typical data of a dam shown in Figure 12 is considered.



Fig. 12 Basic Dimension of Earth Dam

The dam is analyzed for two cases, visavis.

1) Homogeneous section having vs =125 m/sec  $\phi$ =32°, c= 50 kN/m², unit weight  $\gamma$  = 20 kN/m³, height of water = 40m.

2) The same dam with a silty-clay core (shown by dotted line) the core having width at crest of 4.0 meter and width at base of 65m having unit weight of  $\gamma_c$ =21 kN/m<sup>3</sup> and shear wave velocity of 220 m/sec, c=85 kN/m<sup>2</sup> and  $\phi_c$ =12°.

Maximum height of water in the reservoir = 40m.

The dam is in Zone IV as per IS-1893 (2002) having importance factor I as 2.0 and R is taken as 2.0 for this case.

Comparison of time periods (in seconds) is shown below:

0.291

3

IS-1893 Seed & Proposed Proposed With clay Mode Mononobe Gazetas (1984)Makdisi Bt=0.0 Bt=10.0 core 1.044 1 1.044 1.046 1.046 1.046 1.085 0.783 2 0.455 0.455 0.455 0.455 0.471 0.338

0.290

0.300

0.299

0.214

0.300

It is observed that by proposed method time periods are in excellent agreement with other established methods for  $B_t = 0$ . However top width having finite dimension ( $B_t$ =10.0m) elongates the time period by about 4% for the fundamental mode- which would be most critical. The clay core being much stiffer than the outer shell has an overall stiffening effect on the dam response when time period gets reduced by 25% than established expression- this is logical.

Accelerations induced in different modes in dam in terms of g is given hereunder.

| Mode | Sa( homogeneous dam) proposed | Sa with clay core(proposed) | Sa as per IS-<br>1893(2002) |
|------|-------------------------------|-----------------------------|-----------------------------|
| 1    | 0.15g                         | 0.21g                       | 0.19g                       |
| 2    | 0.30g                         | 0.30g                       | NA                          |
| 3    | 0.30g                         | 0.30g                       | NA                          |

Acceleration induced for first three modes by proposed method is as shown above, it is evident that depending on time period value the acceleration variesunlike recommendation of IS code that suggests a constant value. Here it is again observed that the clay core stiffening the overall response- attracts more acceleration than a homogeneous dam.

Modal displacement of dam crest is given below:

| Mode       | u(mm):<br>homogeneous dam | u(mm):<br>with clay core |
|------------|---------------------------|--------------------------|
| 1          | 675                       | 683                      |
| 2          | -135                      | -98                      |
| 3          | 55                        | 40                       |
| SRSS value | 690                       | 692                      |

The modal response is found to be quite high though within acceptable limit. Here it is observed that stiffening effect of impermeable core induces more acceleration and also induces a higher displacement in fundamental mode though the SRSS values are almost same.

The lateral seismic coefficient for the dam is given hereunder.

| Dam type            | αh    |
|---------------------|-------|
| Homogeneous section | 0.183 |
| With clay Core      | 0.250 |
| As per IS code      | 0.190 |

Following the same trend as expressed earlier, the lateral seismic coefficient for the heterogeneous dam is higher- this reflects the importance of considering the heterogeneous effect rather than ignoring it – as is the practice- as of now. It may however be noted that the values were obtained based on damping value D = 5% for all cases .For clay core with high plasticity damping is usually high thus considering 7% damping for the homogeneous dam and 10% for the dam with clay core value of  $\alpha_h$  will come to 0.16 and 0.20 respectively.

Force transmitted to outer and inner shell based on stiffness distribution is outlined below:

| Dam section | Lateral Seismic coeff( $\alpha_h$ ) | Force(kN) |
|-------------|-------------------------------------|-----------|
| Outer core  | 0.053                               | 7268      |
| Inner Core  | 0.118                               | 16228     |

The minimum factor of safety of dam under various load combinations is given below:

| Load Case                           | FOS<br>(Reservoir<br>full) | FOS<br>(Reservoir empty) |
|-------------------------------------|----------------------------|--------------------------|
| Under Static load                   | -                          | 3.47**                   |
| Under Earthquake-<br>Homogenous Dam | 1.60                       | 2.01                     |
| Under earthquake-<br>with clay core | 1.71                       | 1.97                     |

Variation of shear stress in the internal core is given in Figure 13.



Fig. 13 Variation of Shear Stress in Inner Core for the Dam with C= 85 kN/m<sup>2</sup> and  $\phi_c$ =12°

# Conclusions

Based on above, it can be concluded that the present paper proposes a formulation that is more generic than the established methods for dynamic analysis of earth dams based on modal response technique. The proposed method can well cater to the dynamic response of

- > Homogeneous section with finite crest width.
- > Variation in soil property along the depth of the dam.
- Heterogeneous section with impermeable clay core.
- A rational formulation of lateral seismic coefficient α<sub>h</sub>

The paper also proposes a modified method for stability analysis of dam that tries to combine the pseudo static slip circle method and sliding block technique to arrive at a rational FOS under earthquake. The technique for evaluation FOS for clay cored dam based on distribution of their static stiffness is novel but have a logical basis.

The analysis being analytical in nature does not require sophisticated software, a simple spread sheet or a MATHCAD shell would suffice for the same.

Effect of stiffness degradation due to large strain and dynamic pore pressure due to transient shock could further enhance this study.

# Notations

The following symbols are used in this paper:

- An = integration constant which is a function of time
- At = area of dam at crest
- A<sub>tc</sub> = area of clay core at crest
- B<sub>b</sub> = base width of dam

- $B_{bc}$  = width of core at base
- Bn = integration constant which is a function of time
- B<sub>tc</sub> = width of core at crest
- Bt = width of crest
- $C_T$  = coefficient to determine time period of dam
- c = cohesion of soil
- F = lateral seismic force
- F<sub>D</sub> = driving force along critical plane
- F<sub>hc</sub> = lateral seismic force on clay core
- F<sub>hs</sub> = lateral seismic force on outer shell
- $F_R$  = resistive force along critical plane
- G = dynamic shear modulus of soil
- G<sub>c</sub> = dynamic shear modulus of core material
- g = acceleration due to gravity
- H = height of dam
- H<sub>w</sub> = height of water in the reservoir
- i = mode number i= 1,2,3,....
- I = importance factor as per IS code
- j = mode number 1,2,3,...
- J<sub>0</sub> = Bessel's function of first kind of order 0
- $J_1$  = first derivative of Bessel's function  $J_0$
- K<sub>ir</sub> = stiffness matrix of dam
- K<sub>st</sub> = static stiffness of dam with clay core
- K<sub>c</sub> = static stiffness of clay core
- m = modular ratio G<sub>c</sub>/G
- m<sub>ij</sub> = modal mass coefficient
- M<sub>ir</sub> = mass matrix of dam
- N = normal reaction on the critical plane of failure
- N<sub>i</sub>, N<sub>r</sub>= modal shape functions
- P = ratio of core and outer shell weight density
- p = hydrodynamic pressure
- pn = normal hydrodynamic pressure of dam slope.
- Q<sub>i</sub> = modal shear force
- q(t) = generalized time function
- $r_{c}~$  = ratio of core area at top to crest area at top
- R = response reduction factor as per IS code

- Sai = modal spectral acceleration
- $S_{aw}$  = spectral acceleration of free field water
- S<sub>di</sub> = modal displacement
- T = time period of dam
- t = time
- u = displacement amplitude of dam
- ü<sub>av</sub> = average seismic acceleration
- V = strain energy density
- V<sub>s</sub> = shear wave velocity
- V<sub>w</sub> = force due to hydrodynamic pressure
- v<sub>w</sub> =velocity of sound in water
- W<sub>cr</sub> = critical weight of soil mass above the failure plane
- X = co-ordinate axes in horizontal direction
- Z = zone factor as per IS code
- z = co-ordinate axes in vertical direction
- α = a parameter defining variation of dynamic modulus of soil with depth
- $\alpha$  = angle of inclination of the dam slope with horizontal axes
- $\alpha_{\rm h}$  = lateral seismic coefficient
- $\alpha_{v}$  = vertical seismic coefficient
- $\alpha_{\rm hc}~$  = lateral seismic coefficient for clay core
- $\alpha_{\rm hs}$  = lateral seismic coefficient for outer shell material
- $\beta_n$  = constants of Bessel's function J<sub>0</sub>
- $\delta~$  = angle of inclination of clay core with horizontal axes
- $\Delta$  = area of the triangular wedge of failure

 $\varepsilon_x, \varepsilon_z, \gamma_{xz}$  = strain in soil medium

- $\phi$  = angle of internal friction of soil
- $\phi_{\rm c}$  = angle of internal friction of clay core
- $\varphi$  = eigen vector of the dynamic system
- $\gamma$  = unit weight of soil
- $\gamma_{\rm c}$  = weight density of core material
- $\gamma_{w}$  = weight density of water
- $\kappa_i$  = modal mass participation factor
- $\lambda$  = eigen value of the system
- $\mu$  = coefficient of friction for soil mass
- v = Poisson's ratio of soil

- $\theta$  = critical angle of failure
- $\rho$  = mass density of soil
- $\tau_{xz}$  = dynamic shear stress induced in soil
- $\omega$  = natural frequency of dam
- $\xi$  = dimensionless parameter z/H
- $\psi$  = dimensionless variable B<sub>b</sub>-B<sub>t</sub>/B<sub>t</sub>
- $\psi_{c}$  = dimensionless variable  $B_{bc}-B_{tc}/B_{tc}$ .

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