Axisymmetric Seepage Flow Through Semi-Infinite Porous Media

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Introduction

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 \mathbf{F}^{or} Axisymmetric Flow through porous media, the Laplace equation in cylindrical coordinates is given by: n cylindrical coordinates is given by :

$$
\nabla^2 \phi = \frac{\partial^2 \phi}{r^2} + \frac{1}{r} \quad \frac{\partial \phi}{\partial r} + \frac{\partial^2 \phi}{\partial z^2} = 0 \quad ...(1)
$$

where ϕ is potential function, r the distance of the point considered in XY

plane and z is the distance along z-axis or the point,

The solution of Equation (1) was obtained by Weber (1919) forthe potential due to an electrified circular disc. The corresponding hydrodynamic problem for the potential due to a circular disc source has been reported by Sneddon (1951) and Lamb (1945).

This solution has also been obtained by Sunde (1946) for the potential due to an elementary flat circular disc of negligible thickness on the surface of the ground at a point on the ground surface e of the ground at a point on the ground surface.

The problem of seepage in the half space can be formulated as below (Figure 1). $(Figure 1)$.

Assuming ^z to be positive vertically downwords

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$$
\nabla^2 \phi = 0 - \infty < z < 0
$$
\n
$$
-\infty < y < \infty
$$
\n
$$
-\infty < x < \infty
$$

on $z=0$,

$$
\phi = -Kh_1 \quad -\infty < x \le -l \\
-a \le y \le a \\
\phi = -Kh_2 \quad l \le x < \infty \\
-a \le y \le a
$$

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FIGURE ¹ : Half space problem.

As is evident it is a mixed boundary value problem involving infinite dimensions. As such, the usual analytical methods, e.g., separation of variables, integral transforms, relaxation, etc., were not found suitable for the solution. ^A numerical method involving the superposition of the known solutions for the potential due to circular discs on the surface of the half plane has been developed. The method has been extended to include the case in which the seepage region is bounded by an underlying horizontal impervious stratum.

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Analysis

The problem described above has been solved by considering the upstream and downstream equipotential regions to consist of a finite number
of signals discs placed ediacent to each other each disc having a constant of circular discs placed adjacent to each other, each disc having a constant potential on its face. These potentials have been so adjusted that when the total effect of all the discs is considered, the potential distribution on the upstream and dowstream regions from where and to which the seepage takes ^place, is constant. Due to the symmetry of the problem, it was found convenient to keep these potentials as $+50$ percent and $$ found convenient to keep these potentials as $+50$ percent and -50 per-
cent respectively. The superposition of the solutions due to elementary disc is permissiable because of the linearity of the Laplace'^s equation. Although the upstream and downstream equipotential surfaces are theoretically of infinite extent, it is clearly not possible in any numerical or experimental method to consider them as such. These surfaces have, there fore, been kept finite. However, the dimensions were determined bysolving the two dimensional problem with finite upstream and downstream equipotential surfaces and determining the size so that the potentials would be reasonably representative of the infinite case. If the canal on either side of the floor is considered lo be 1.5 times the length of the floor, the potential distribution will be close to those obtained by considering theequipotential regions extending to infinity (Satish Chandra, 1968).

(a) *Infinite Depth of the Porous Media*

To evaluate the potential due to the upstream and downstreamTo evaluate the potential due to the upstream and downstream cons-
tant potential regions from where and to which the seepage takes place,
the method of superposition of potentials due to discs has been used as method of superposition of potentials due to discs has been usedas-
suming these regions to be finite. These two regions *B* & *C* of size $2a \times 2b$
suming these regions to be finite. These two regions *B* & *C* of size $2a \times 2b$ are symmetrically located on either side of the *Y* axis extending from $x = l$

FIGURE ² : Disc arrangement.

a to to $x = +(l+2b)$ and $x = -l$ to $x = -(l+2b)$ and about the x-axis from $y=-a$ (Figure 2). Each s along the *Y* axis and $(n+1)$ discs along *x* axis. of these regions a to $y = -a$ (Figure 2). Each of these regions is assumed to contain $(2m+1)$
discs along the Y axis and $(n+1)$ discs along y axis

In this analysis the two constant potential regions *B* &In this analysis the two constant potential regions $B & C$ have been
assumed to have the length equal 2*np* and width 4 *mp*. These two regions assumed to have the length equal *2np* and width 4 mp. These two regions have been assumed to be separated by a distance $2l = 2gp$. For the two have been assumed to be separated by a distance $2l = 2gp$. For the two dimensional seepage by assuming the constant potential regions to be finite and equal to 3l (2l being length of the floor) the potentials obtained at different points along the floor are within 0.2 percent of those obtained when the constant potential regions extend to infinity on either side. Thus, by assuming $2 np = 3gp$, the finite regions of constant potential have been considered to represent the regions extending to infinity considered to represent the regions extending to infinity.

From the requirements of the problem the resultant potential, after From the requirements of the problem the resultant potential, after interference, due to all the discs everywhere on the regions $B \& C$ has to he constant and of the some positive and propriety the planetic structure. be constant and of the same positive and negative strenghts respectively.

For this purpose the strength distribution of the discs on the region *B & ^C* was determined so that the resulting potentials on *^B & ^C* regions were constant as required.

Having determined the potential strength of the individual discs, the resulting potential at any point $(\alpha P, \beta p)$ can be obtained. The potential distribution in the region between the two constant potential regions on $z = 0$ plane have been computed.

*(,b***)** *Finite Depth of Porous Media*

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For evaluting the potentials due to seepage throughFor evaluting the potentials due to seepage through the porous media of finite depth the method of images has been employed. For seepage through a media of depth T , an infinite number of similar regions of discs ^a media of depth *T,* an infinite number of similar regions of discs as for the infinite medium problem discussed earlier, placed vertically above and below these regions at distances equal to $2T$ $4T$ $6T$ and so on and belowabove and below these regions at distances equal to 2*T*, $4T$, $6T$ and so on have been considered which will make the plane $z = T$ an impervious boundary, and the plane $z = 0$ also an impervious boundary surface, except boundary, and the plane $z=0$ also an impervious boundary surface, except
for the regions of constant potential. (Figure 2) the regions of constant potential. (Figure 3).

Potential Distribution with Confined Seepage Below Floor Level

The method developed, has been used to determine the potential dis tribution on the area between the constant potential regions for infiniteand finite depths of the pervious medium of infinite areal extent. The problems have been solved on digital computer. have been solved on digital computer.

In case of infinite depth of the previous medium, the p° tentials have been determined for the following seven combinations of the *g, ^m* and *ⁿ* values:

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The first four combinations of *g, ^m*The first four combinations of g , m and n correspond to a coarse
mesh of discs forming the regions from where and to which the seepage mesh of discs forming the regions from where and to which the seepage takes place representing the length width ratio of the floor of 3, $3/2$, 1, and $1/3$ representing T_5 are length width ratio of the floor of 3, $3/$ rakes place representing the length width ratio of the floor of 3, $3/2$, 1, and $1/3$ respectively. To ascertain the effect of using a finer mesh of discs and $1/3$ respectively. To ascertain the effect of using a finer mesh of discs
the order three combinations have been used to give length-width ratios of the order three combinations have been used to give length-width ratios of 3, 2 and 1 respectively. Due to the limitation on the size of the com-
puter it was not possible to try a still finer mesh. The length-width ratio of $1/3$ was used to ascertain how close the potentials obtained by this of 1/3 was used to ascertain how close the potentials obtained by this method correspond to the theoretical two dimensional seepage potentials potentials already known. The strength of the discs forming the regions from where and to which the seepage takes place and the resulting potentials under
the floor region for all the cases have been determined. e floor region for all the cases have been determined.

In case of finite depth of the medium, the strengths of the discs, forming the region from where the seepage takes place, have been determined ming the region from where the seepage takes place, have been determined for only one condition, i.e., for *g.m. n* and *T* values of 6, 2, 9 and 6 res-

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pectively to establish this method and to determine the potential distribution under the floor for finite depth of porous medium. under the floor for finite depth of porous

To compare these results with those obtained by electrical analogy
que, experiments were conducted for his idea technique, experiments were conducted for length-width ratio of 1, 2 and
3 in an electrical analogy tank, and the potentials width ratio of 1, 2 and 3 in an electrical analogy tank, and the potentials obtained.

Infinite Depth of Medium

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(a) *Strength Distribution*

 On examining the strength distribution it is observedstrength of the discs increase from the middle to the edges of the plate. On moving along the *X* direction (Figure 2) away from the floor, the $\frac{1}{2}$ strengths first reduce and then increase towards the ends. Among the Y-
strengths first reduce and then increase towards the ends. Among the Ydirection the strengths are minimum on the X axis and increase towards the edges. the edges.

Increase in the width of the ^plates (increase in *^m*Increase in the width of the plates (increase in m values) reduces the strength magnitude of all the discs, but the strength distribution pat tern, remains the same. The strength distribution of the discs on *^X*axis and at $x = g$ along Y axis have been presented in Figure 4. These

strength distributions pertain to coarse and fine set of discs $L/B = 1$ of the floor, i.e., g *, m, n* values of 6, 3, 9 & 12, 6, 18 respectively. It is observed that by making the mesh finer (i.e., by increasing the number of discs on the constant potential regions), the strength distribution of the discs on the region is the same as with coarser mesh but the magnitude of strengths for all the discs is slightly reduced.

(b) Potentials along Centre line

The potentials along the centre line of the floor, for the length-width (I/R) of 1/2, 1, 2/2 and 2 with ratio (L/B) of $1/3$, 1 , $3/2$ and 3 with coarse and 1 , 2 , 3 with fine mesh α Figure (L/D) of 1/3, 1, 3/2 and 3 with coarse and 1, 2, 3 with fine mesh of disc forming the constant potential regions respectively have been plotted in Figure 5. in Figure 5. The potential distribution under the floor for two dimensions In Figure 5. The potential distribution under the floor for two dimensional
seepage have also been presented for comparison. It is observed that the potentials on the upstream half of the floor decrease by increasing the lengthwidth ratio, whereas on the downstream half of the floor the potentials increase by increasing the length-width ratio. The same trend has been ob-
served for the coarse and fine mesh of discs. The results abtained experiserved for the coarse and line mesh of discs. The results abtained experi-
mentally by electrical analogy method also indicate the same trend. theoretically, by decreasing the length-width ratio the potential distri-
Theoretically, by decreasing the length-width ratio the potential distribution should approach that for two dimensional seepage. Also the poten bution should approach that for two dimensional seepage. Also the potentials on the upstream half for all the length-width ratio should be lower than those for two-dimensional seepage while on the downstream half these
than those for two-dimensional seepage while on the downstream half these
should be higher. It has been observed that for the coarse mesh these be higher. It has been observed that for the coarse mesh these potentials are always more on the upstream side and less on the downstream side than those two dimensional seepage. In accordance with the theoretical expectation, for all the length-width ratios of the floor consider expectation, for all the length-width ratios of the floor considered, with fine mesh, the potentials on the downstream side are more than these for two dimensional express present for \vec{L} is a dimensional openion of \vec{L} is a dimensional express of \vec{L} is a dimensional expres those for two dimensional seepage except for $L/B = 1$ close to the downstream end. It may be concluded that if the computer size would permit a still finer mesh than that considered here, this would ^give the desiredpotential distribution on the floor with greater accuracy.

The effect of change in the L/B ratio on the magnitude of potentials has been observed to be maximum at the quarter points, the floor being ² percent for change of *L/ B* ratio from ¹ to 2 and 1.5 percent for change of L/B ratio from 2 to 3. The magnitude of the change reduces to \overline{R} zero on moving towards the centre and ends of the floor. On comparing these results with the experimental results, it is found that on the downstream half of the floor the potentials obtained experimentlly are higher
than these aktivited by the mathed of diese (Figures 6, 7 and 8). This than those obtained by the method of discs (Figures 6, ⁷, and 8). This difference is expected to be eliminated if a finer mesh of discs is used to represent the constant potential regions. The results obtained by electrical analogy experiments at U.S. Waterways Experimental Station (1963) have also been presented in these figures. These results comare well with the results obtained in the present investigation. The minor differences *are due to the use of different tank and model dimensions in the* two investigations.

(c) *Potential Distribution Across the Floor*

Referring to Figures 6, 7 and 8, it is observed that on the downstream half of the floor the potentials along the edge are higher than those on the central line for all length-width ratios. The same trend has been observed with the computed and experimental results. The maximumdifference in the end line and central line potentials is about 3 perce enterful the end line and central line potentials is about 3 percent
in computed and 4 percent in experimental resuls for all the lengthwidth ratios. This maximum difference is at about one tenth of the length from the ends of the floor reducing towards the centre and end engun from the ends of the floor reducing towards the centre and ends
where there is no difference in potentials at the sides and at the central
line.

FIGURE 6: Potential distribution under the floor (L/B=1)

FIGUre 7: Potential distribution under the floor $(L/B=2)$.

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The potential distribution at the level of the floor computed in the Figure 9ose to the constant potential plates has been presented in

Finite Depth of the Medium

The potentials below the floor for seepage through ^a pervious medium of finite depth equa^l to half the length of the floor with length-

FIGURE ⁹ : Potential distribution at floor level (L/B=2, fine mesh of discs)

width ratio of ² have been ^plotted in Figure 10. For comparison the potentials obtained with the same length-width ratio and infinite depth of pervious medium and same number of discs representing the constant potential regions, have also been ^plotted, for the downstream half of the floor. The central and edge line potentials for finite depth of the mediumare found to be lower than those for infinite depth of the medium. The maximum difference in potentials has been observed at distances of 0.2 *L* from the ends reducing to zero towards the centre and ends of the floor.

In two dimensional seepage for the finite depth of the medium equal to $(L/2)$, the difference in potentials is within 1 percent of those for the infinite medium (Leliavsky, 1965). The larger difference in three dimensional seepage is due to the larger concentration of stream lines towards the sides.

Conclusions.

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Using this method it has been found that the potential due to three dimensional seepage in half space with infinite depth of the medium are higher than those for two dimensional seepage under the downstream half of the floor, and under the upstream half of the floor lower than those for two dimensional case

By increasing length-width ratio, these potentials increase for thedownstream half of the floor and decrease for the upstream half. This has been confirmed experimentally also confirmed experimentally also.

The reduction in depth of the pervious stratum has been found to reduce the potentials on the downstream half of the floor and increase on e the potentials on the downstream half of the floor and increase on the upstream half of the floor. This is similar to that for the two-dimensional seepage.

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FIGURE 10: Potential distribution under the floor $(L/B=2, 2)$ finite dcpth medium)

Notations

 $\frac{2}{B}$ Width of the impervious floor Coordinates of a point along x -axis B_p $\begin{array}{ccc} B_{p} & = \\ 2_{p} & = \end{array}$ **Coordinates of ^a joint along y-axis**

Finite length of the seepage region of constant potential $\begin{bmatrix} 2_p \\ 2_p \end{bmatrix}$ =

K $=$ **permeability of the medium.**

 L $\begin{matrix} 2i \\ L \end{matrix}$ $\begin{matrix} \} = \end{matrix}$ **length of the impervious floor**

 $2_{g_{\mathcal{P}}}$ J

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potential function

P \equiv **radius of the elementary disc**

- **radial distance** *r* \equiv
- *T* **Finite depth of the pervious region** $\overline{}$
- *X***distance along x-axis** \equiv
- *Y***distance along y-axis** $\qquad \qquad =$
- **Zdistance along z-axis** $=$

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